

- Sparse coding is often performed over several consecutive vectors, i.e. audio frames or image patches.
- We propose a multivariate sparse coding algorithm to decompose several frames simultaneously.
- We compare the performance of a *global* sparsity prior over several frames, versus a frame-wise sparsity prior.

“Frame by frame” sparse coding

Sparse coding of multiple frames x_1, \dots, x_T :

$$\hat{x}_t = \operatorname{argmin}_{x_t} \|y_t - Dx_t\|_2^2, \text{ s.t. } \|x_t\|_0 < K \quad \forall t = 1, \dots, T \quad (1)$$

⇒ each frame is processed **individually**

⇒ sparsity is enforced **framewise**, with parameter K

Algorithm 1 IHT for multiple signals

```

for  $t = 1, \dots, T$  do                                ▷ Loop over frames
  initialize:  $x_t^0 = 0$ 
  while  $\|y_t - Dx_t^n\|_2^2 > \epsilon$  do
     $x_t^{n+1} = x_t^n + \mu D^T(y_t - Dx_t^n)$            ▷ Gradient descent
     $x_t^{n+1} \leftarrow \mathcal{H}_K(x_t^{n+1})$                  ▷ Hard Thresholding
  return  $\{x_t\}_{t=1..T}$ 
  
```

⇒ **Limitations:**

- Sparsity parameter K might be difficult to choose (K might vary between frames)
- vector x_t might not be sparse (ex: transients in audio)
- how to enforce sparsity *across* frames? (ex: sparsity over time)

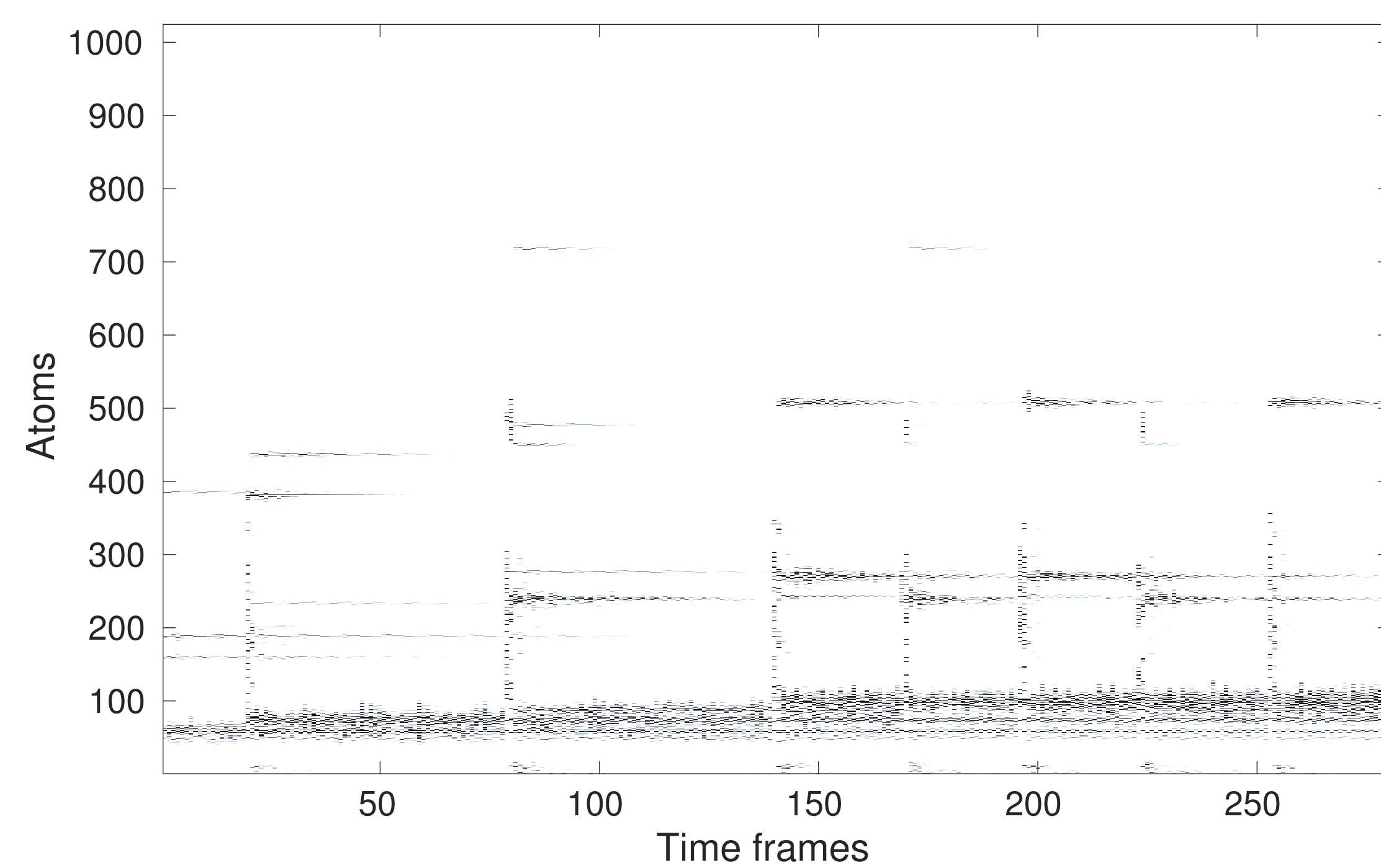


Figure: Sparse coding of $T=280$ frames from a glockenspiel signal, using $K=32$ atoms by frame, i.e. 8960 coefficients in total. SNR = 21.7 dB

Multivariate sparse coding

We define $Y = [y_1, \dots, y_T] \in \mathbb{R}^{N \times T}$ as the matrix containing T adjacent frames concatenated altogether, and $X = [x_1, \dots, x_T] \in \mathbb{R}^{M \times T}$ the corresponding sparse activation matrix.

Proposition:

- Reformulate the cost function in (1) in a **multivariate** way
- Introduce a **global** sparsity prior:

$$\hat{X} = \operatorname{argmin}_X \|Y - DX\|_F^2 \quad \text{s.t.} \quad \|X\|_0 < K_{\text{tot}} \quad (2)$$

$$= \operatorname{argmin}_{x_1, \dots, x_T} \sum_{t=1}^T \|y_t - Dx_t\|_2^2 \quad \text{s.t.} \quad \sum_{t=1}^T \|x_t\|_0 < K_{\text{tot}} \quad (3)$$

- We introduce a *masking matrix* \mathcal{M} in order to enforce the stopping criterion $\|Y_t - DX_t^{n+1}\|_2^2 \leq \epsilon$

Algorithm 2 Multivariate IHT with global sparsity

```

Require:  $Y, D, \epsilon, K_{\text{tot}}, \mu, \mathcal{M} = \mathbf{1}_{M \times T}$ 
initialize:  $X^0 = 0, n = 0$ 
while  $\exists t$  s.t.  $\|Y_t - DX_t^n\|_2^2 > \epsilon$  do
   $X^{n+1} = X^n + \mu \mathcal{M} \otimes (D^T(Y - DX^n))$ 
   $X^{n+1} \leftarrow \mathcal{H}_{K_{\text{tot}}}^{\text{global}}(X^{n+1})$            ▷ Global Hard Thresholding
  for  $t = 1, \dots, T$  do
    if  $\|Y_t - DX_t^{n+1}\|_2^2 \leq \epsilon$  then
       $\mathcal{M}_t \leftarrow \mathbf{0}_M$                                ▷ Update mask
  return  $X$ 
  
```

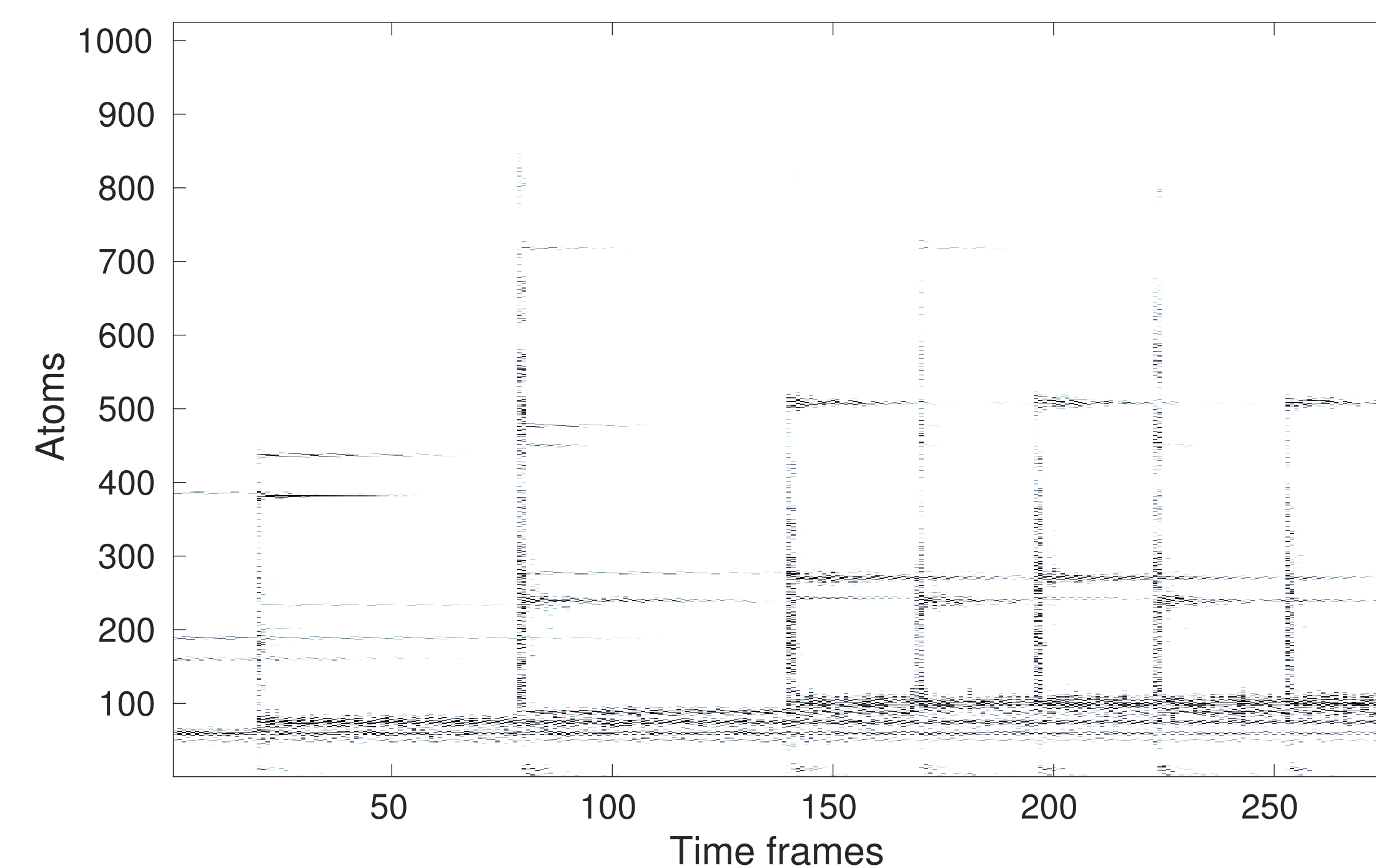


Figure: Sparse coding of the same signal, using a global sparsity prior with $K_{\text{tot}} = 8960$ atoms in total, using the proposed Multivariate IHT algorithm. SNR = 31.8 dB. The proposed approach manages to recover tonal components as well as transients.

Advantages of proposed approach:

- Frames are processed simultaneously, which allows for more flexible sparsity patterns
- Sparsity is enforced **on average**, which means that more dense frames can “borrow” coefficients from sparser frames

Experiments

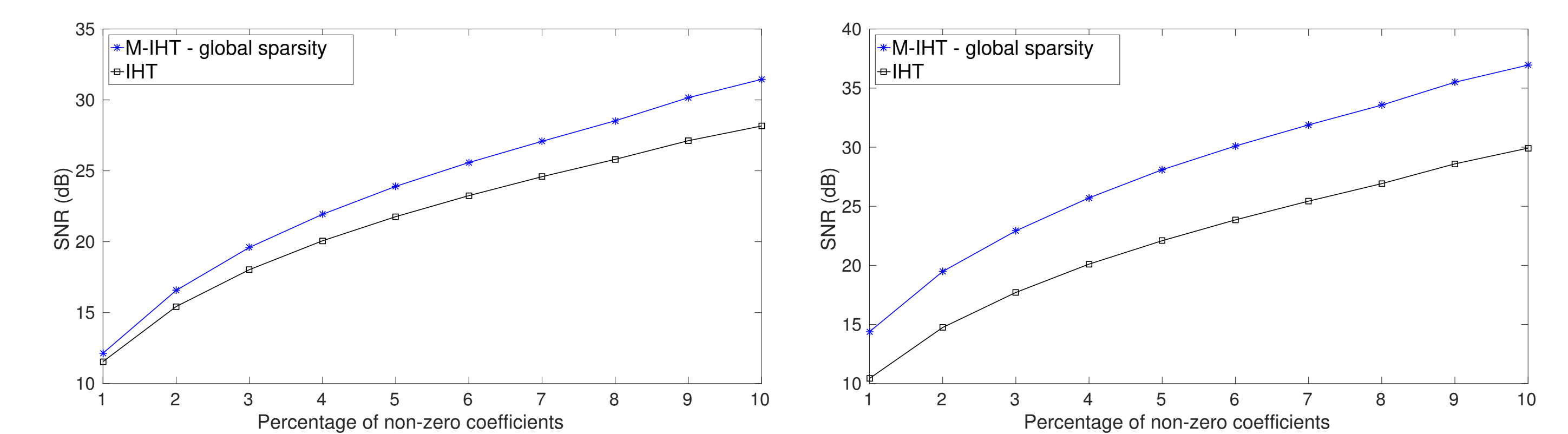


Figure: Audio coding experiment. SNR of reconstructed signal, as a function of the percentage of non-zero coefficients. Left: music signals. Right: speech signals.

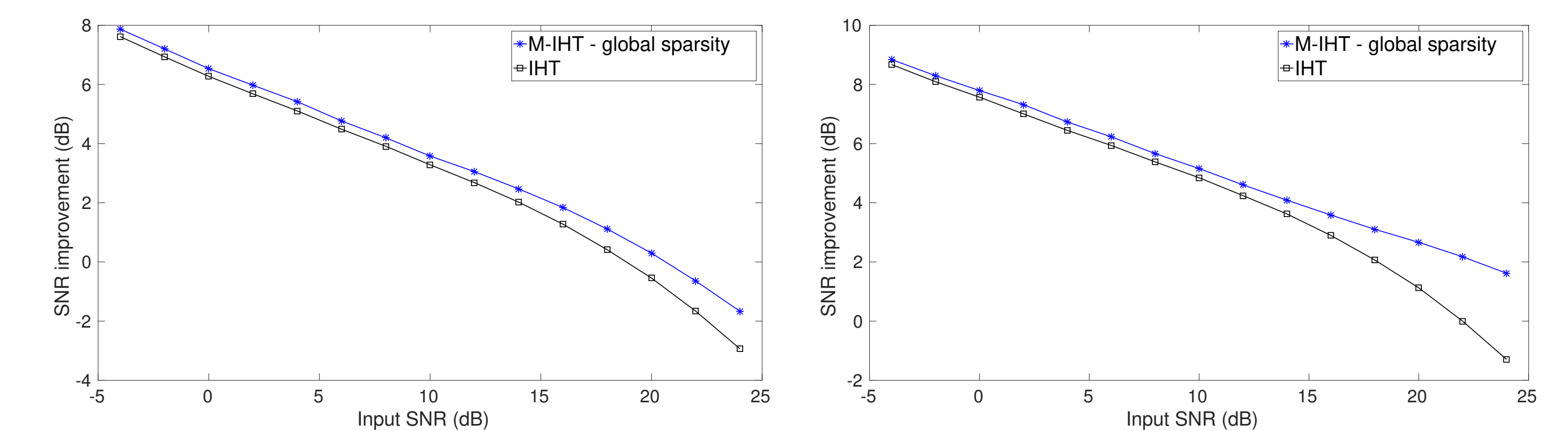


Figure: Audio denoising experiment. SNR improvement of the reconstructed signal, as a function of the input SNR. Left: music signals. Right: speech signals.

	IHT	Multivariate IHT with global sparsity
CPU time (s)	20.8	2.0

Table: Average CPU time to process 1s of signal (in Matlab).

Conclusion

- Multivariate IHT allows to process several frames simultaneously, thus more flexible sparsity patterns.
- A *global* sparsity prior performs better than a frame-wise sparsity prior, allowing both very sparse and very dense frames to be efficiently represented simultaneously.
- Multivariate IHT is much faster (in Matlab) than the classic IHT.